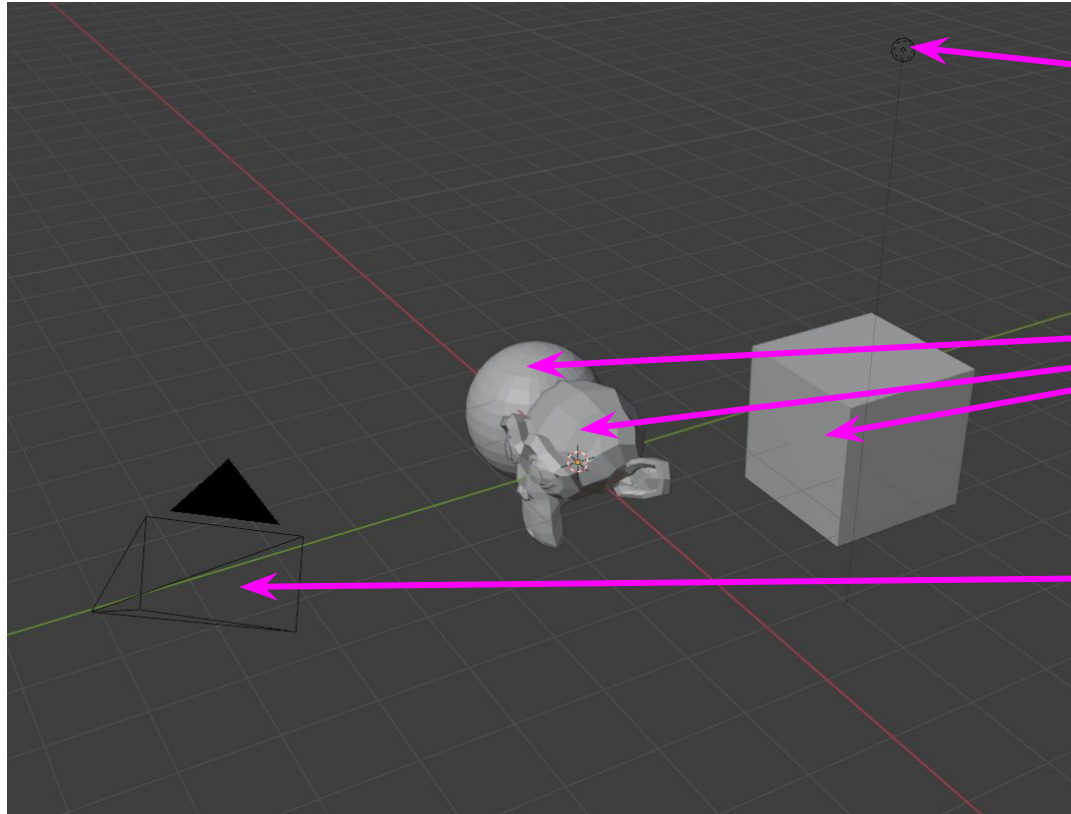


3D Graphics

The rendering pipeline

Reminder : Scene



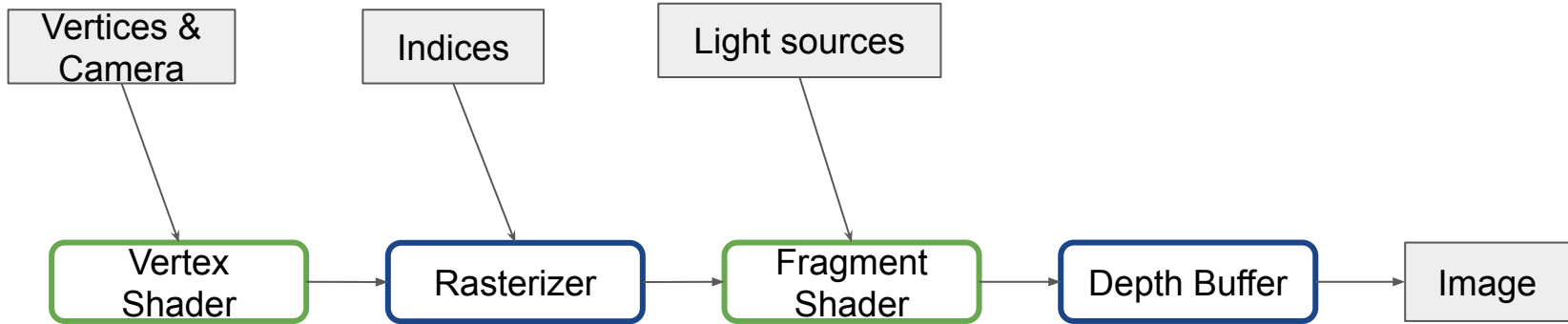
Light Source

3D Objects

Camera

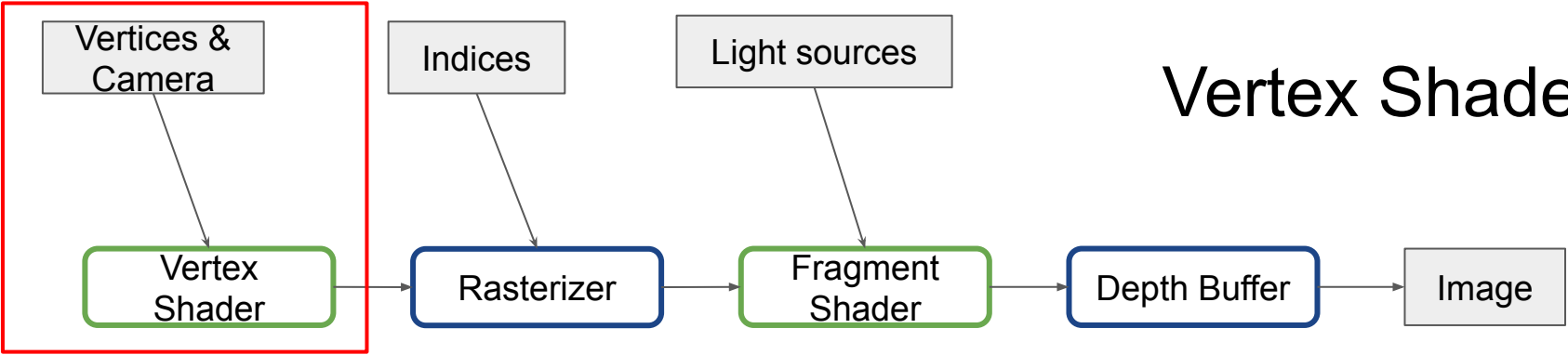
The rendering pipeline

Helps us go from a 3D scene to a 2D image



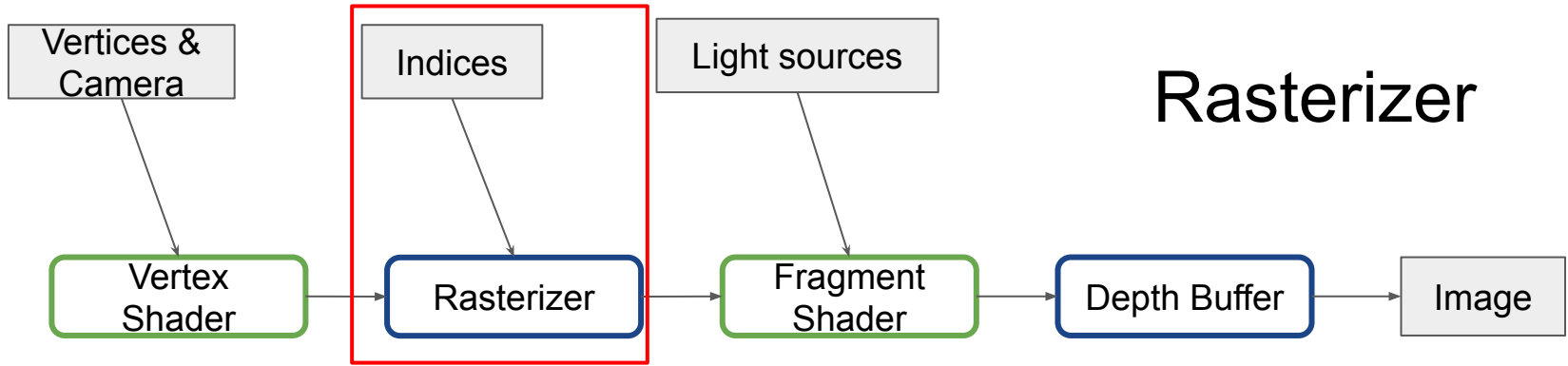
Minimal rendering pipeline

Vertex Shader



Re-express vertices in the camera coordinates system

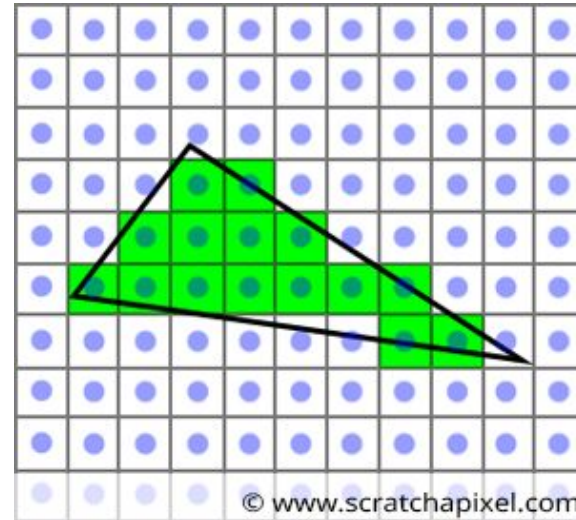
Project vertices in the frustum

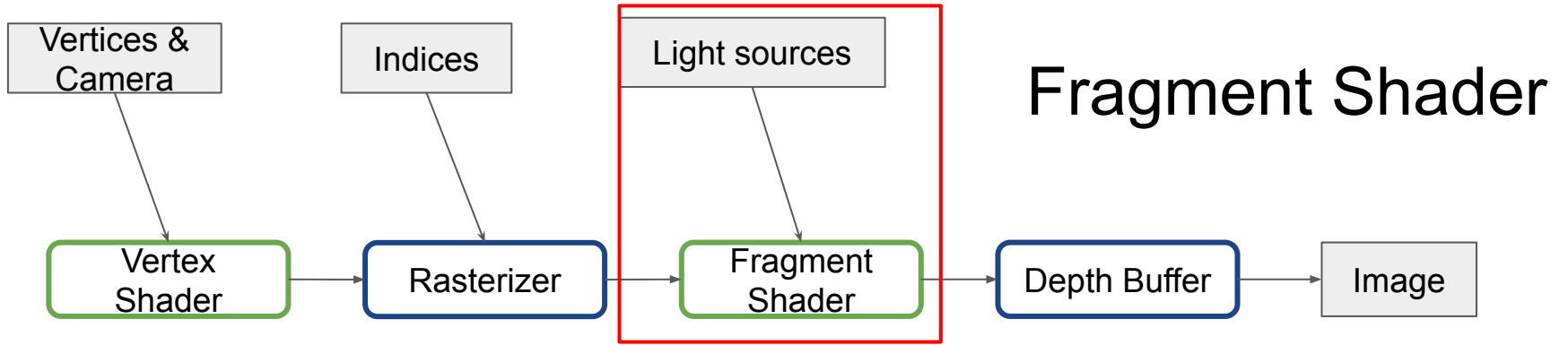


Rasterizer

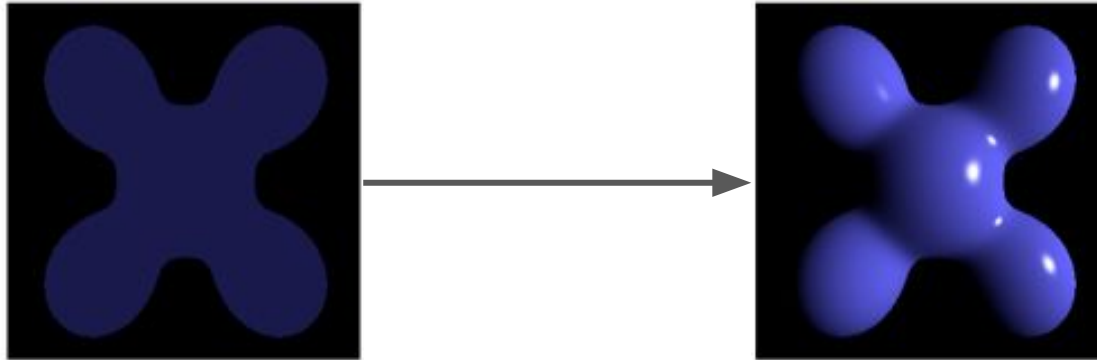
Find which pixel is inside which triangle

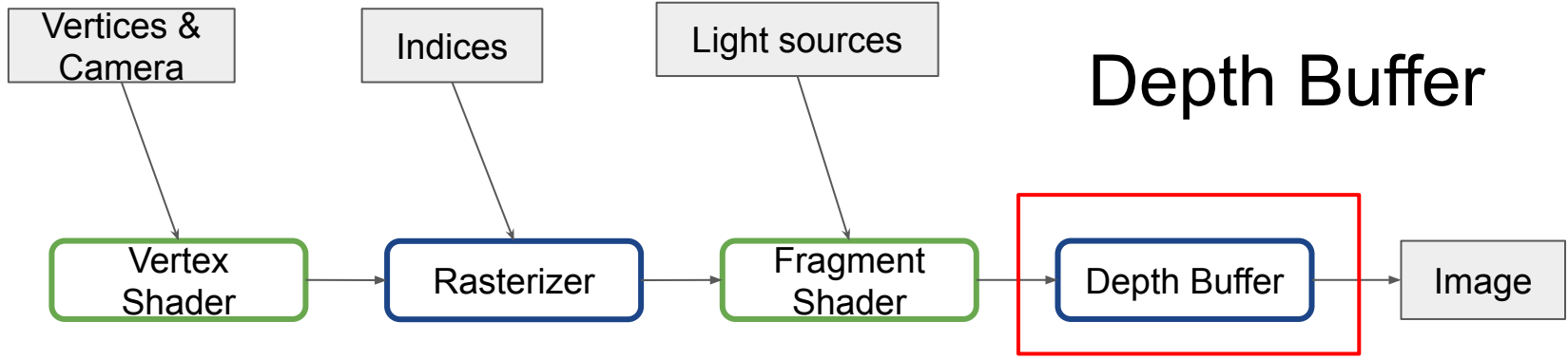
Emit fragments (candidates pixel)



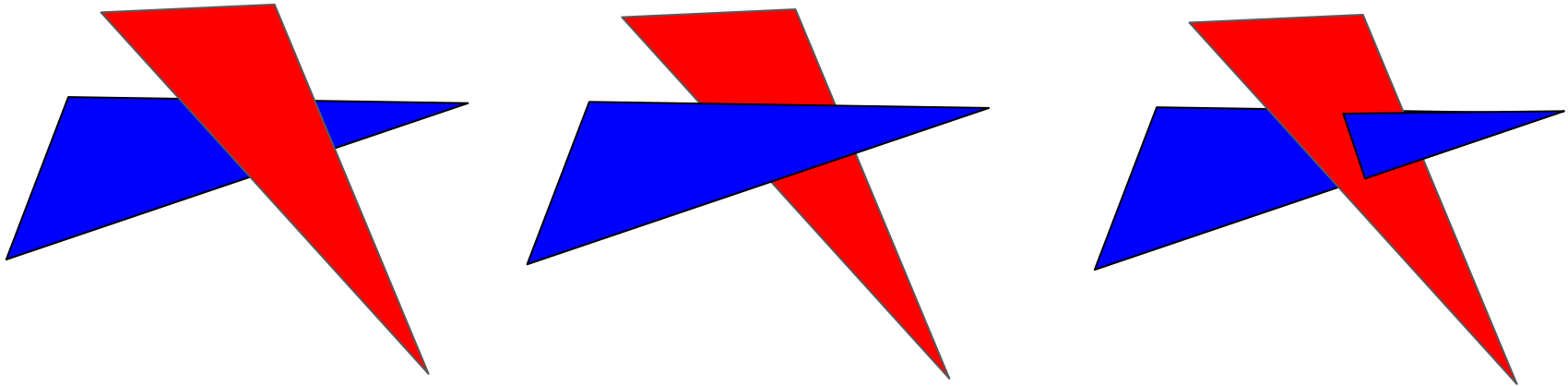


Compute the color to give each fragments

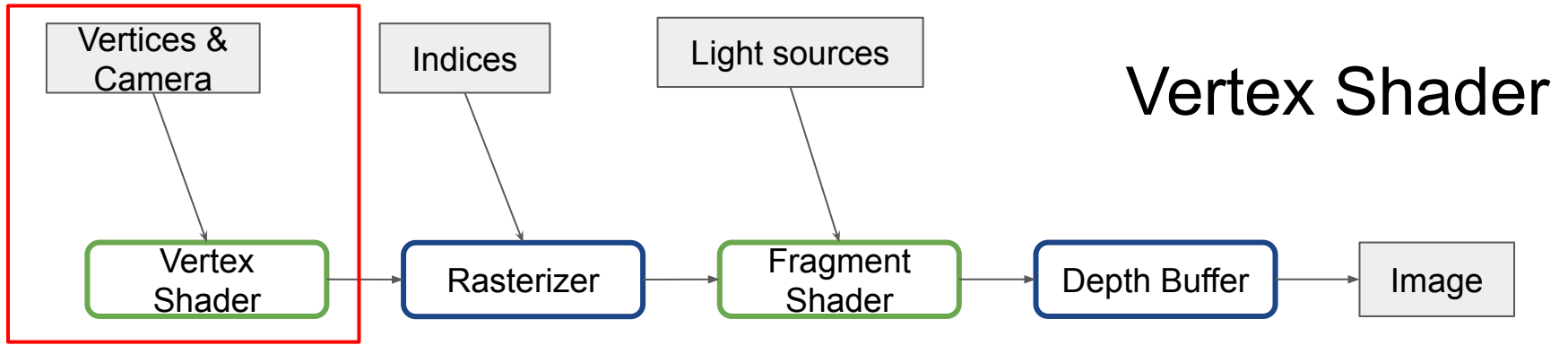




Choose which Fragment get to become a pixel using a Depth test



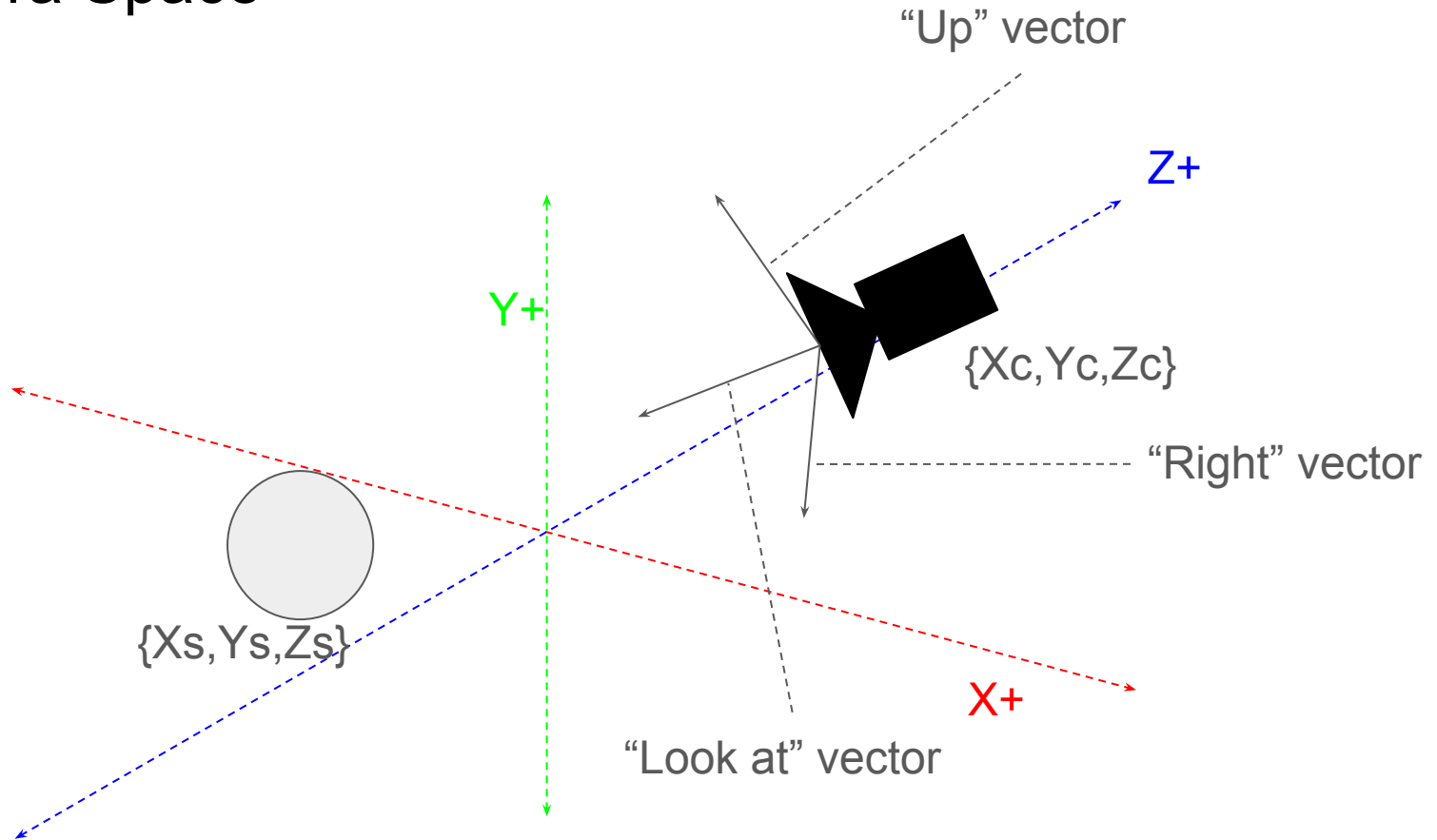
Vertex Shader



Re-express vertices in the camera coordinates system

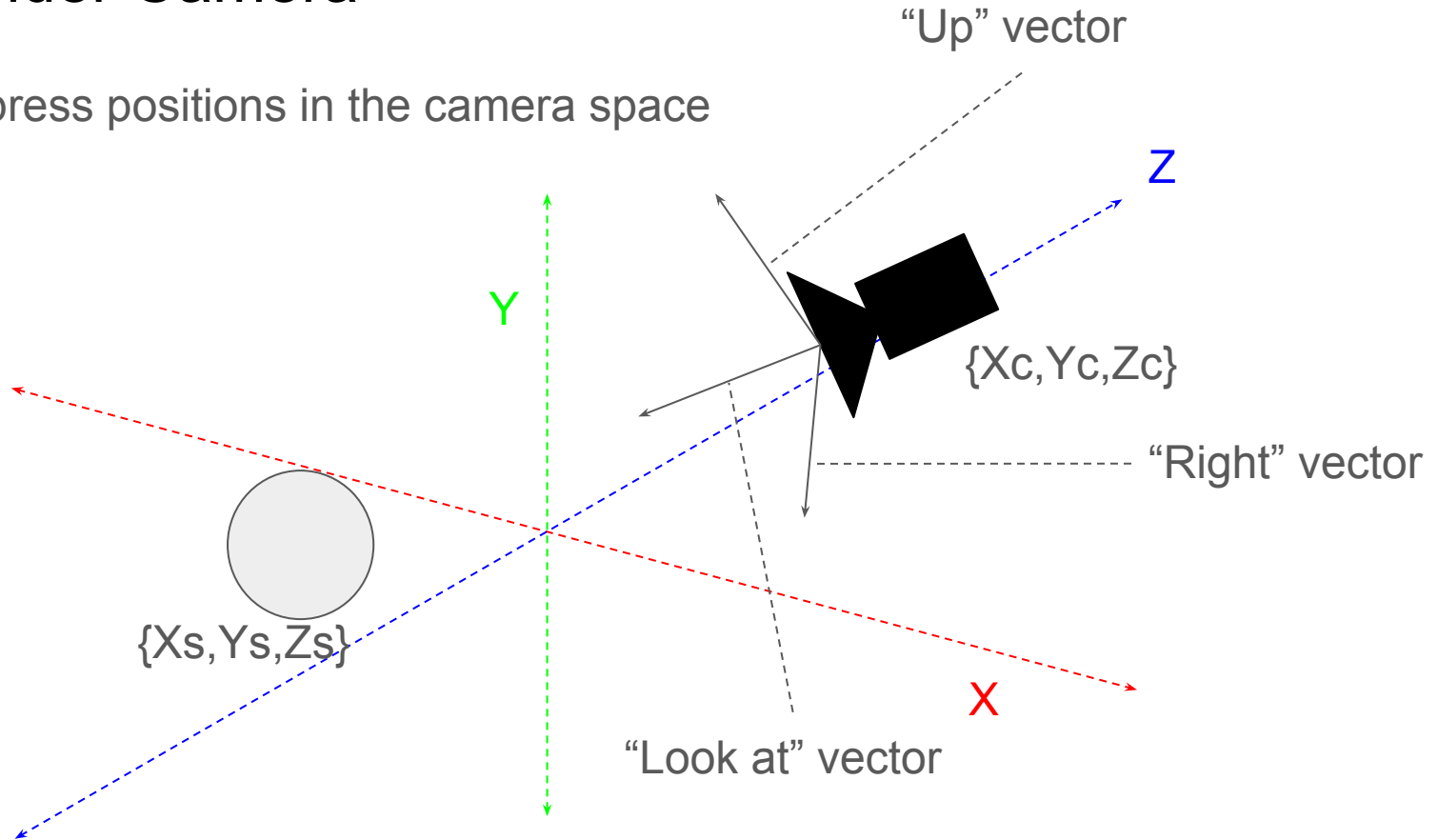
Project vertices in the frustum

Camera Space



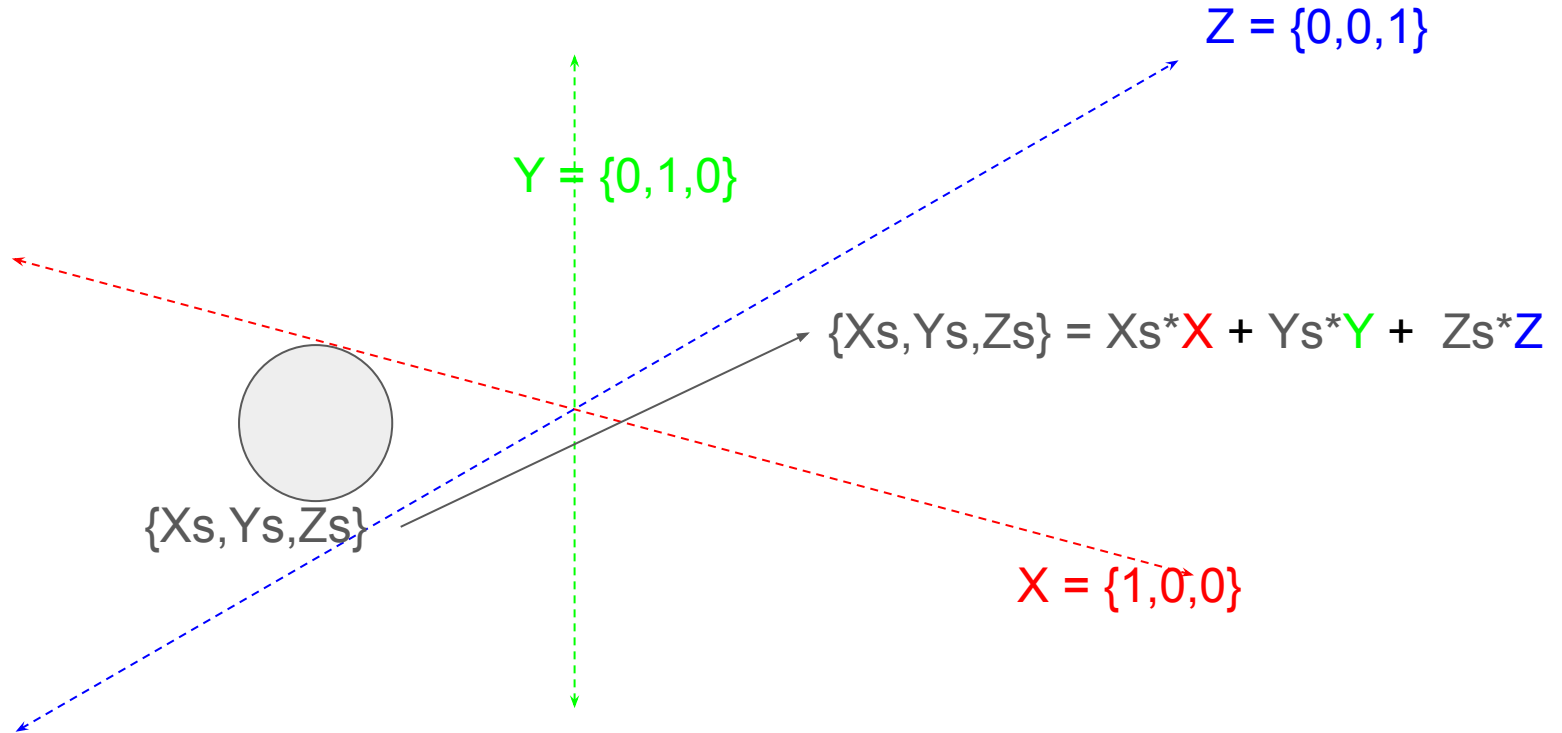
Reminder Camera

Re-express positions in the camera space



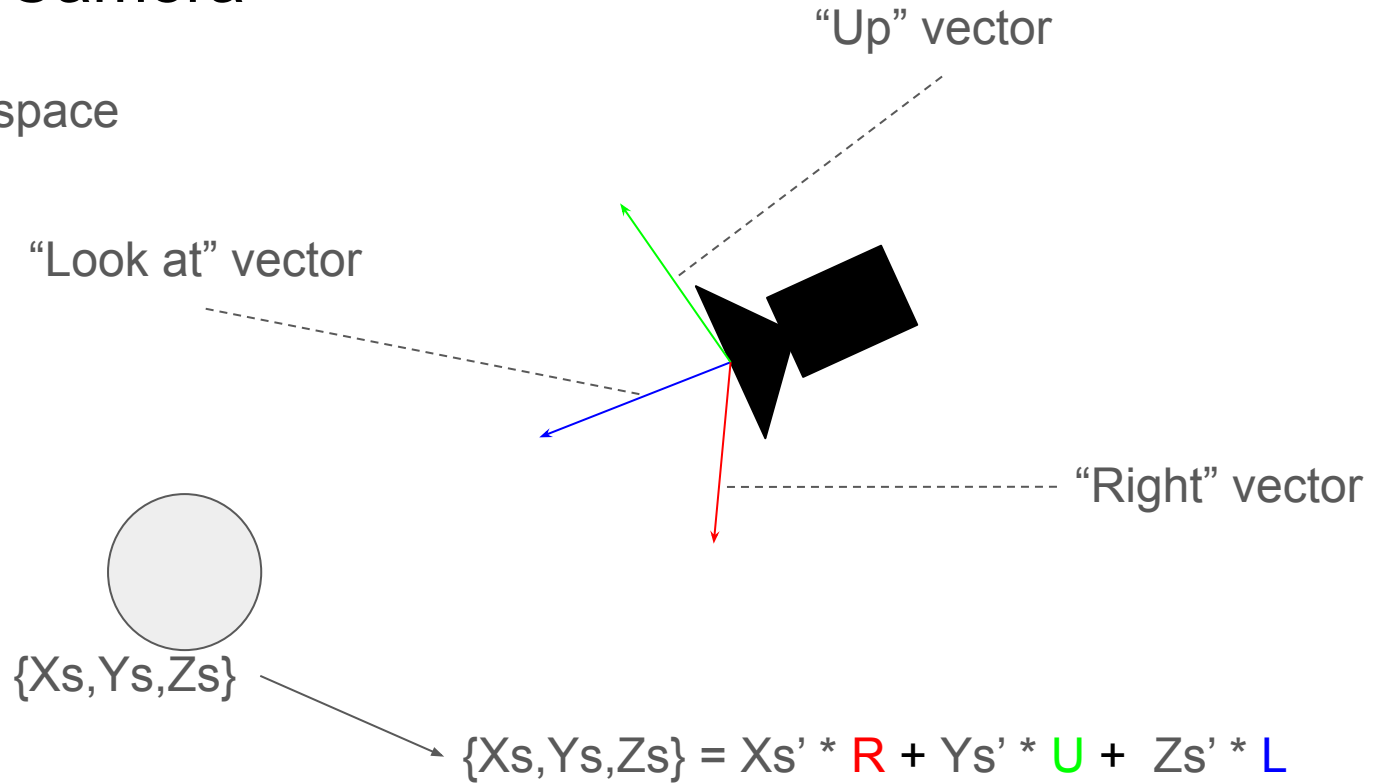
Reminder Camera

Our current coordinates :



Reminder Camera

The camera space



Reminder Camera

The Mathematical problem

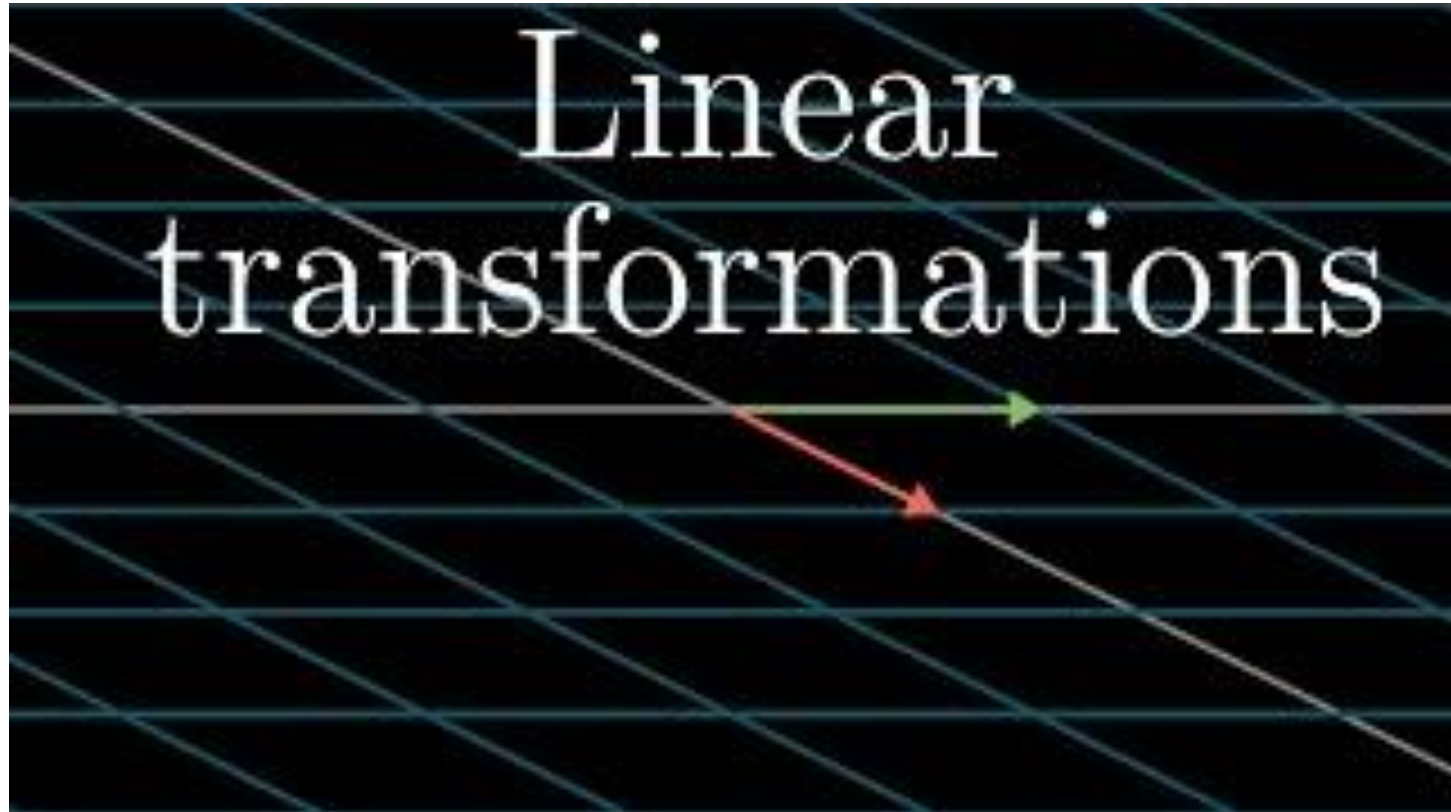
$$\{X_s, Y_s, Z_s\} = X_s' * R + Y_s' * U + Z_s' * L$$

$$\{X_s, Y_s, Z_s\} = X_s * X + Y_s * Y + Z_s * Z$$

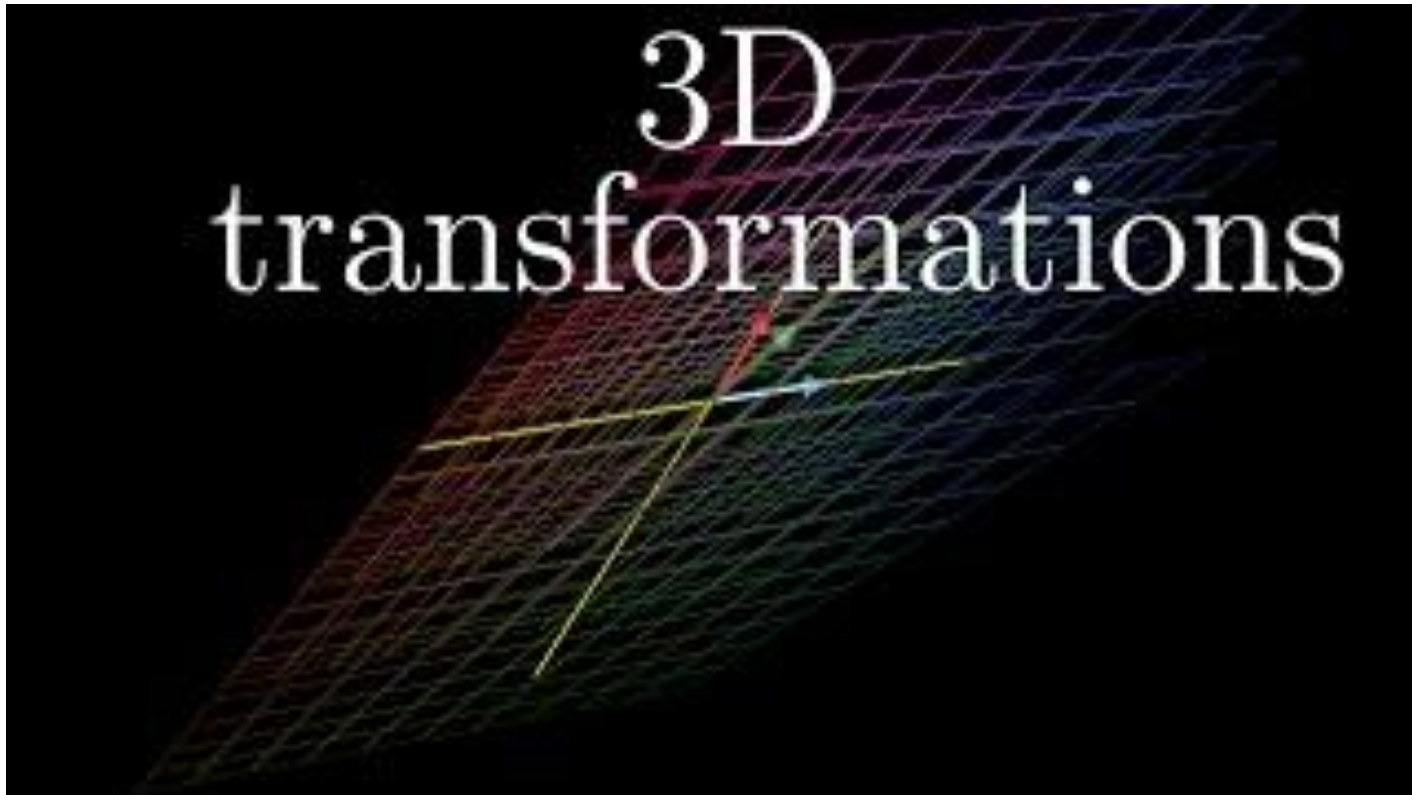
$$X_s * X + Y_s * Y + Z_s * Z = X_s' * R + Y_s' * U + Z_s' * L$$

The problem Find X_s' , Y_s' , and Z_s'

Linear Transformations



Linear Transformations



Question :

$$X_s * X + Y_s * Y + Z_s * Z = X_{s'} * R + Y_{s'} * U + Z_{s'} * L$$

What is the matrix that solve this problem

(1 minute alone)

(2 minutes with your neighbors)

(5 minutes with the whole group)

Question :

$$X_s * X + Y_s * Y + Z_s * Z = X_{s'} * R + Y_{s'} * U + Z_{s'} * L$$

“Right” vector

“Look at” vector

$$\begin{bmatrix} X_s \\ Y_s \\ Z_s \end{bmatrix} = \begin{bmatrix} Rx & Ux & Lx \\ Ry & Uy & Ly \\ Rz & Uz & Lz \end{bmatrix} \begin{bmatrix} X_{s'} \\ Y_{s'} \\ Z_{s'} \end{bmatrix}$$

“Up” vector

Question :

$$X_s * X + Y_s * Y + Z_s * Z = X_{s'} * R + Y_{s'} * U + Z_{s'} * L$$

“Right” vector

“Look at” vector

$$\begin{bmatrix} X_{s'} \\ Y_{s'} \\ Z_{s'} \end{bmatrix} = \begin{bmatrix} Rx & Ux & Lx \\ Ry & Uy & Ly \\ Rz & Uz & Lz \end{bmatrix}^{-1} \begin{bmatrix} X_s \\ Y_s \\ Z_s \end{bmatrix}$$

“Up” vector

Question :

$$X_s * X + Y_s * Y + Z_s * Z = X_{s'} * R + Y_{s'} * U + Z_{s'} * L$$

“Right” vector

“Look at” vector

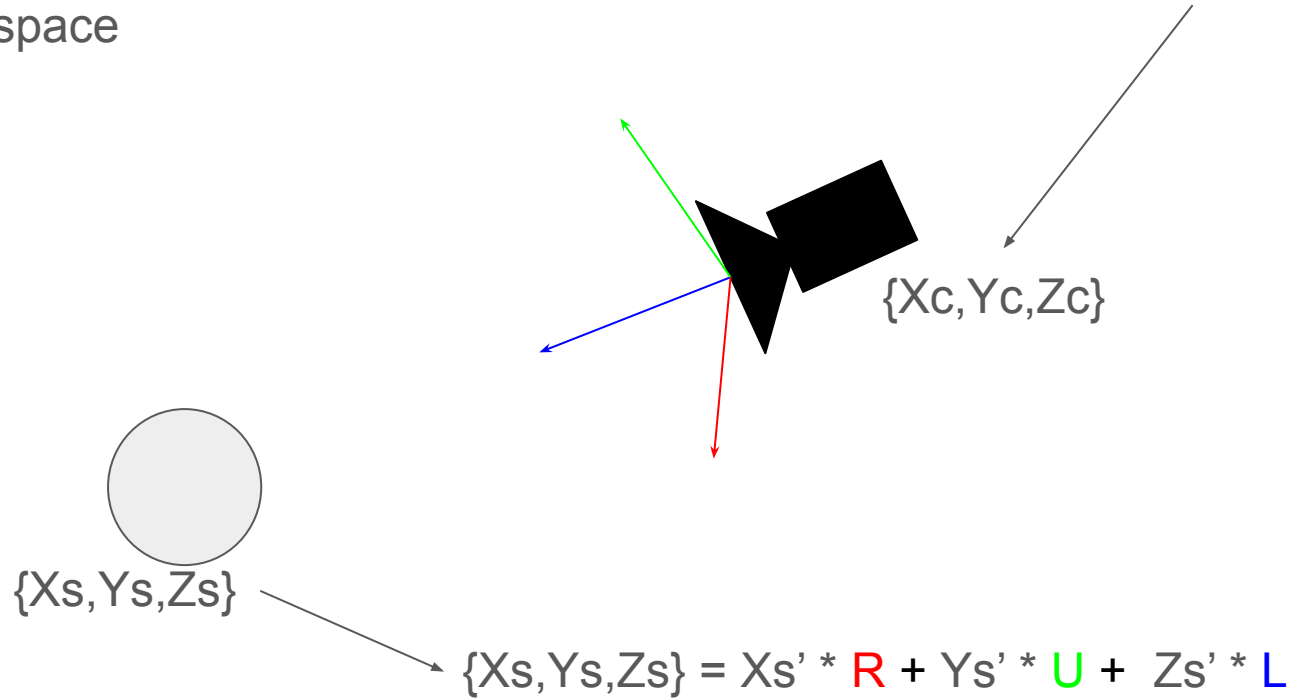
$$\begin{bmatrix} X_{s'} \\ Y_{s'} \\ Z_{s'} \end{bmatrix} = \begin{bmatrix} R_x & R_y & R_z \\ U_x & U_y & U_z \\ L_x & L_y & L_z \end{bmatrix} \begin{bmatrix} X_s \\ Y_s \\ Z_s \end{bmatrix}$$

“Up” vector

Problem with Linear transformations

The camera space

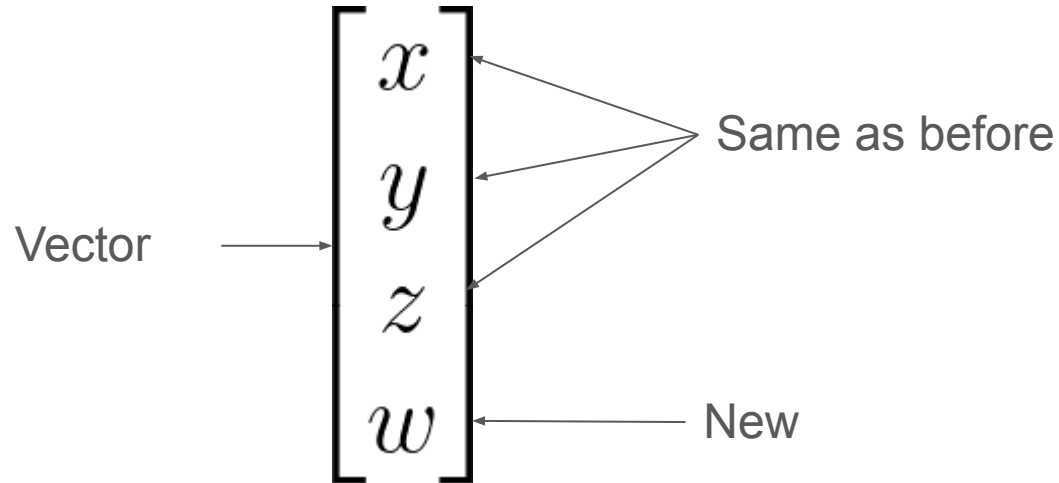
What about the camera coordinates ?



Homogeneous Coordinates

Allow us to “move” the origin of the frame

Using 4 coordinates instead of 3 : Homogeneous coordinates



Linear Transformation

$$X_s * X + Y_s * Y + Z_s * Z = X_{s'} * R + Y_{s'} * U + Z_{s'} * L$$

$$\begin{bmatrix} X_{s'} \\ Y_{s'} \\ Z_{s'} \\ W_s \end{bmatrix} = \begin{bmatrix} Rx & Ry & Rz & 0 \\ Ux & Uy & Uz & 0 \\ Lx & Ly & Lz & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} X_s \\ Y_s \\ Z_s \\ W_s \end{bmatrix}$$

Affine Transformation

General case

$$\begin{bmatrix} x + wTx \\ y + wTy \\ z + wTz \\ w \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & Tx \\ 0 & 1 & 0 & Ty \\ 0 & 0 & 1 & Tz \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix}$$

Affine Transformation

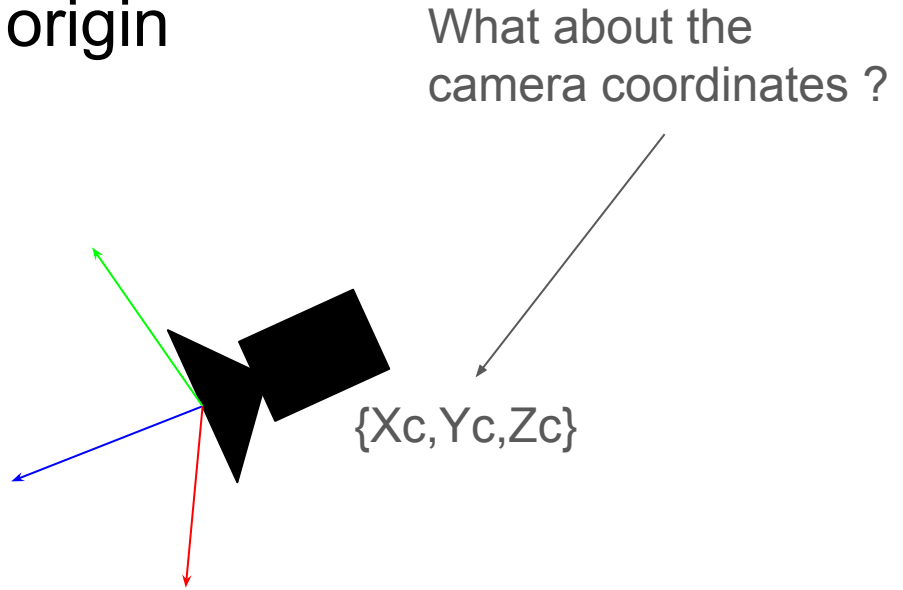
For a vertex: $w = 1$

$$\begin{bmatrix} x + Tx \\ y + Ty \\ z + Tz \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & Tx \\ 0 & 1 & 0 & Ty \\ 0 & 0 & 1 & Tz \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

 Add the vector T to the vertex

Translate the camera to the origin

$$\begin{bmatrix} 1 & 0 & 0 & -X_c \\ 0 & 1 & 0 & -Y_c \\ 0 & 0 & 1 & -Z_c \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



Camera Space

$$\begin{bmatrix} X_{s'} \\ Y_{s'} \\ Z_{s'} \\ W_s \end{bmatrix} = \begin{bmatrix} Rx & Ry & Rz & 0 \\ Ux & Uy & Uz & 0 \\ Lx & Ly & Lz & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -X_c \\ 0 & 1 & 0 & -Y_c \\ 0 & 0 & 1 & -Z_c \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} X_s \\ Y_s \\ Z_s \\ W_s \end{bmatrix}$$

Matrix multiplication



Camera Space

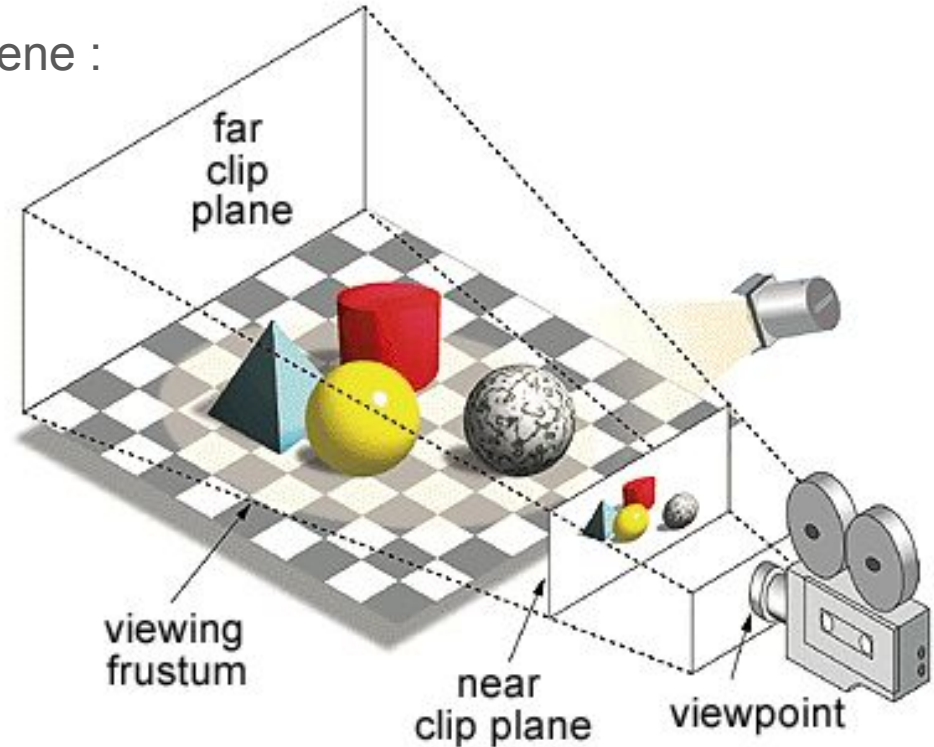
View Matrix \leftarrow

$$\begin{bmatrix} Rx & Ry & Rz & 0 \\ Ux & Uy & Uz & 0 \\ Lx & Ly & Lz & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -Xc \\ 0 & 1 & 0 & -Yc \\ 0 & 0 & 1 & -Zc \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Reminder: Camera

Frustum : the visible part of the scene :

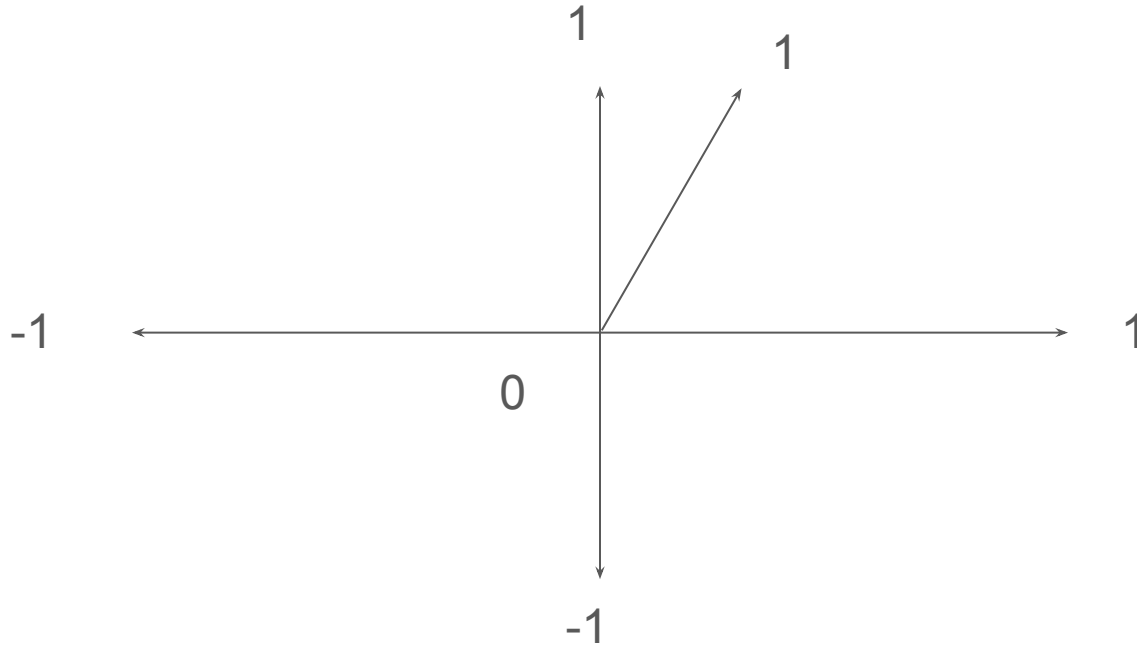
- Near plane
- Far plane
- Aspect ratio
- Field of View



Projection Perspective

Objective : we want to express the visible space in the following space

x in $[-1,1]$
 y in $[-1,1]$
 z in $[0,1]$



Perspective Projection matrix

- Near plane = n
- Far plane = f
- Aspect ratio = a
- Field of View = fov

$$s = \frac{1}{\tan(fov/2)}$$

$$\begin{bmatrix} s/a & 0 & 0 & 0 \\ 0 & s & 0 & 0 \\ 0 & 0 & \frac{f}{f-n} & -\frac{f*n}{f-n} \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Problem

After the projection the w coordinate of the vertex is modified.

To solve this issue we normalize all vertex coordinates by dividing them by w

Summary Vertex shader

For each vertex v , the vertex shader compute a vertex v' such that :

$$v_{tmp} = [proj] [view] v$$

$$v' = \frac{v_{tmp}}{v_{tmp} \cdot w}$$